

**UNIVERSITY OF CALIFORNIA AT BERKELEY**  
**College of Engineering**  
**Dept. of Electrical Engineering and Computer Sciences**

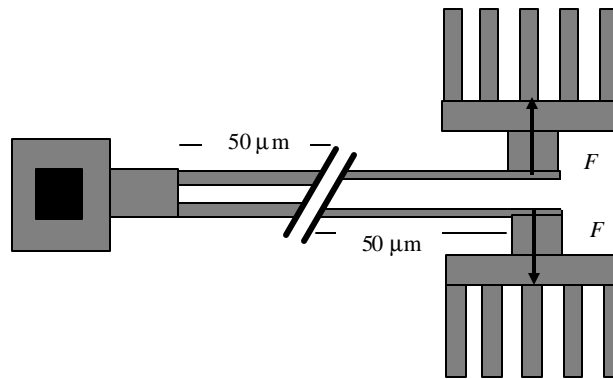
**Problem Set #4**

**Due Thursday, October 9, 2003, 5:00 pm**

**EECS C245 / ME C218**

**Fall 2003**

1. The layout below shows a single-ended, comb-drive tuning fork resonator made from a 2  $\mu\text{m}$ -thick polysilicon film. The length of the tines is 100  $\mu\text{m}$  and their thickness is  $h = 2 \mu\text{m}$  in the bending direction for the first 50  $\mu\text{m}$  from the shoulder of the tuning fork, after which the thickness is 1  $\mu\text{m}$ . The area of the interdigitated comb fingers and their attachment structures at the end of each tine is 168  $\mu\text{m}^2$ .



- a) Use the Principle of Virtual Work to estimate the linear spring constant for one of the tines, when deflected by the force  $F$ .

a) assume  $y(x) = C_2 x^2 + C_3 x^3$   
 strain energy:  $W_{\text{bend}} = \int_0^L \frac{1}{2} E I_y(x) \left( \frac{d^2 y}{dx^2} \right)^2 dx$   

$$= \frac{1}{2} E \frac{A}{12} \int_0^L \frac{W^3(x)}{W} (2C_2 + 6C_3 x)^2 dx$$
  

$$W(x) = \begin{cases} W_2, & 0 < x < L/2 \\ W/2, & L/2 < x < L \end{cases}$$
  

$$= \frac{E W^3 h}{24} \int_0^{L/2} (2C_2 + 6C_3 x)^2 dx + \frac{E (W/2)^3 h}{24} \int_{L/2}^L (2C_2 + 6C_3 x)^2 dx$$
  

$$W_{\text{bend}} = \left( \frac{E W^3 h}{128} \right) \{ 12 C_2^2 L + 22 C_2 C_3 L^2 + 15 C_3^2 L^3 \}$$
  
 Potential energy:  $U = W_{\text{bend}} - F y(L)$  for point load at end of beam  

$$\begin{cases} \frac{\partial U}{\partial C_2} = 0 = \frac{E W^3 h}{128} \{ 24 C_2 L + 44 C_3 L^2 \} - F L^2 \\ \frac{\partial U}{\partial C_3} = 0 = \frac{E W^3 h}{128} \{ 44 C_2 L^2 + 30 C_3 L^3 \} - F L^3 \end{cases}$$
  

$$C_2 = \frac{256}{59} \left( \frac{F L^2}{E W^3 h} \right); \quad C_3 = \frac{64}{59} \frac{F}{E W^3 h}$$
  
 Spring constant  $k = \frac{F}{y(L)} = \frac{F}{\frac{256}{59} \left( \frac{F L^2}{E W^3 h} \right) + \frac{64}{59} \left( \frac{F L^3}{E W^3 h} \right)} = \left( \frac{59}{320} \right) \frac{E W^3 h}{L^2}$   

$$k = 0.47 \mu\text{N}/\mu\text{m}$$
  
*\* note softer than uniform-thickness cantilever*

- b) Estimate a tine's effective mass, for a fundamental mode. You can use your deflection function from part (a) as the mode shape.

$$b) y(x, t) = y(x) \cdot \cos \omega t$$

$$K_{max} = \int_0^L \frac{1}{2} \rho W(x) h \omega^2 y^2(x) dx$$

$$y(x) = \frac{256}{59} \frac{FL}{EW^3h} \cdot x^2 + \frac{64}{59} \frac{F}{EW^3h} x^3$$

$$= \frac{64}{59} \left( \frac{F}{EW^3h} \right) \cdot [4L \cdot x^2 + x^3] = A x^2 (x + 4L)$$

$$y^2(x) = A^2 [x^4 (x^2 + 8Lx + 16L^2)]$$

$$= A^2 (x^6 + 8Lx^5 + 16L^2x^4)$$

$$K_{max} = \frac{1}{2} \rho W h \omega^2 A^2 \int_0^{L/2} (x^6 + 8Lx^5 + 16L^2x^4) dx + \frac{1}{2} \int_{L/2}^L (x^6 + 8Lx^5 + 16L^2x^4) dx$$

$$K_{max} = \frac{1}{2} \rho W h \omega^2 \left( \frac{64}{59} \right)^2 \left( \frac{F}{EW^3h} \right)^2 (2.40 L^7)$$

Define  $M_{eff}$  of beam:  $K_{max} = \frac{1}{2} M_{eff} \omega^2 y^2(L)$

$$\left( \frac{320}{59} \right)^2 \left( \frac{FL^3}{EW^3h} \right)^2$$

$$\text{Solve for } M_{eff} = \frac{1}{25} (2.4) \rho W h L$$

$$\text{Total effective mass} = M_{eff, tot} = M_{comb} + M_{eff}$$

$$= \rho \cdot \underbrace{A_{comb} \cdot h}_{168 \mu m^2} + \frac{2.4}{25} \rho W h L$$

$$\underline{M_{eff, tot} = 0.87 \text{ mg}}$$

- c) Estimate the fundamental resonant frequency  $f_1$  of the tuning fork using the Rayleigh-Ritz method.

$$c) K_{max} = W_{max} \text{ from (b) and (a)}$$

$$\omega = \sqrt{\frac{k}{M_{eff, tot}}} = \left[ \frac{0.47 \text{ N/m}}{0.87 \times 10^{-9} \times 10^{-3} \text{ kg}} \right]^{1/2} = 735 \text{ rad/s}$$

$$\underline{f = \frac{1}{2\pi} \omega = 117 \text{ kHz}}$$

2. Double-ended tuning forks (DETF) are potentially useful as frequency references for communication circuits. As the amplitude of vibration increases, the tuning fork's deflection is no longer proportional to the applied load. In this problem, use the mode shapes provided in Lecture 9 as trial functions. You can neglect the residual stress in the tines.

- a) Given that the DETF is driven in the fundamental anti-symmetric mode and that the displacement at the center of the beam is  $y$ , use the principle of virtual work to estimate the dependence of the applied force  $F$  (concentrated in the beam's center) on  $y$  for large displacements. Your answer should include a term proportional to  $y^3$ .

② a) Use normalized mode shape from lecture:

$$y_1(x) = C \kappa [\sinh \beta \epsilon - \sin \beta \epsilon + \alpha (\cosh \beta \epsilon - \cos \beta \epsilon)]; \quad \epsilon = x/L$$

↑ parameter for variation of  $\nu$ .

$$\int_0^L \left( \frac{d^2 y_1}{dx^2} \right)^2 dx = \frac{1}{L^3} \int_0^1 \left( \frac{d^2 y_1(\epsilon)}{d\epsilon^2} \right)^2 d\epsilon = \frac{198.5 C^2}{L^3}$$

$$\int_0^L \left( \frac{dy_1}{dx} \right)^2 dx = \frac{1}{L} \int_0^1 \left( \frac{dy_1(\epsilon)}{d\epsilon} \right)^2 d\epsilon = \frac{4.85 C^2}{L}$$

Strain in beam (following lecture):  $\epsilon_x = \epsilon_{\text{bend}} + \epsilon_{x, \text{axial}}$  self-generated, no S.

$$W = \frac{1}{2} E W \int_0^L \int_{-h/2}^{h/2} \epsilon_x^2 dy dx = -\nu y' \frac{d^2 y}{dx^2} + \frac{1}{2L} \int_0^L \left( \frac{dy}{dx} \right)^2 dx$$

$$= \frac{1}{2} E W \int_0^L \left[ \frac{h^3}{12} \left( \frac{d^2 y}{dx^2} \right)^2 + \left( \frac{4.85}{2L^2} \right)^2 C^2 h \right] dx$$

$$= \frac{1}{2} E W \left[ \frac{h^3}{12 L^3} (198.5 C^2) + 5.88 \frac{h}{L^3} C^4 \right]$$

Require  $\frac{\partial U}{\partial C} = \frac{\partial}{\partial C} (W - F \cdot C) = 0$

$$\therefore F = 16.54 \left( \frac{E W h^3}{L^3} \right) \underbrace{C}_{y_1} + 23.52 \left( \frac{E W h}{L^3} \right) \underbrace{C^3}_{y_1^3}; \quad y_1(L/2) = C \phi(1/2) = C$$

b) Now consider that the DETF is driven in its *second mode* by concentrated forces (each called  $F$ ) applied at the locations of the peak displacement  $y$ . What is the functional relationship between  $F$  and  $y$ ?

b) Corrected coefficients for second mode:  $\alpha = -0.29$ ,  $\beta = 7.85$ ,  $\kappa = -0.663$

$$\int_0^1 \left( \frac{d^2 y_2(\epsilon)}{d\epsilon^2} \right)^2 d\epsilon = 1676 C^2 \quad \int_0^1 \left( \frac{dy_2(\epsilon)}{d\epsilon} \right)^2 d\epsilon = 20.1 C^2$$

o analysis is the same as for (a) with new integrals.

$$W = \frac{1}{2} E W \left[ \frac{h^3}{12 L^3} \cdot 1676 C^2 + \frac{(20.1)^2}{4 L^3} h C^4 \right]$$

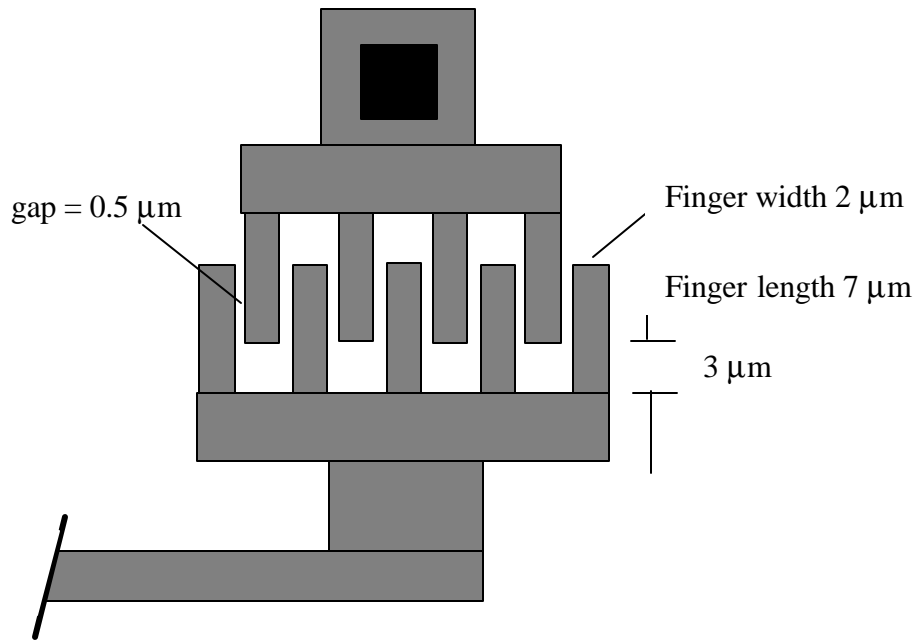
$$\frac{\partial U}{\partial C} = \frac{\partial [W - 2 F C]}{\partial C} = 0 \quad * \text{ note work done is } 2 F C$$

$$\cdot \frac{1676}{12} \left( \frac{E W h^3}{L^3} \right) C + (20.1)^2 \frac{E W h}{L^3} C^3 = 2 F$$

$$F = 69.8 \left( \frac{E W h^3}{L^3} \right) \underbrace{y_2}_{y_2} + 202 \left( \frac{E W h}{L^3} \right) \underbrace{y_2^3}_{y_2^3}$$

↑ factor of  $\sim 4 \times$  higher than for  $y_1$       ↑ factor of  $\sim 8 \times$  higher than for  $y_1$

3. The layout below shows a detailed view of the complete comb-drive from Prob. 1. The tuning fork is suspended  $2\ \mu\text{m}$  above the substrate.



- a) The tuning fork voltage is  $V_p = 5\ \text{V}$  and a drive voltage  $v_d(t) = 5\ \text{mV} \cos(2\pi f_1 t)$  is applied to the upper tine's comb drive. Find the drive force  $f_d(t)$  at the frequency  $f_1$ .

3. a)  $V_p = 5\ \text{V}$ ,  $v_d(t) = 5\ \text{mV} \cos \omega t$

$$F_c = \frac{1}{2} V_{rs}^2 \frac{dC_{rs}}{dx} ; C_{rs} = \frac{2N\epsilon_0 t}{g} \cdot x ; N=4, t=2\ \mu\text{m}, g=500\ \text{nm}.$$

$$= \frac{1}{2} (V_p - v_d(t))^2 \left( \frac{2N\epsilon_0 t}{g} \right)$$

$$= \frac{N\epsilon_0 t}{g} V_p^2 - \frac{2N\epsilon_0 t}{g} V_p \hat{v}_d \cos \omega t + \left( \frac{N\epsilon_0 t}{g} \right) \hat{v}_d^2 \cos^2 \omega t.$$

$$F_d(t) = \underbrace{3.54\ \text{nN}}_{\text{DC}} - \underbrace{7.08\ \text{pN}}_{\text{drive force amplitude}} \cos \omega t.$$

neglect small contribution to DC force.  $\rightarrow \left\{ \frac{1 + \cos 2\omega t}{2} \right\}$

- b) Using the Couette and squeeze-film models from Lecture 9, estimate the quality factor of this resonator at a pressure of 100 mTorr.

b) Note: W. Slack's Ph.D. thesis has a typo for  $\mu_p$ : the correct value is  $3.7 \times 10^{-2} \text{ kg m}^{-2} \text{ s}^{-1} \text{ Torr}^{-1}$

$$b_{\text{Comette substrate}} = \frac{\mu A}{y_0} = \frac{\mu_p p y_0 A}{y_0} \quad A = 168 \mu\text{m}^2, y_0 = 2 \mu\text{m}$$

$$b_{\text{Comette fingers}} = \mu_p p A_f \quad A_f = (4 \times 2 \mu\text{m}^2) \times 8 = 64 \mu\text{m}^2$$

$$b_{\text{Comette}} = \mu_p p (A + A_f) = (3.7 \times 10^{-2}) (0.1) (168 + 64) \times 10^{-12} \text{ m}^2 \text{ Torr}^{-1} \text{ kg m}^{-2} \text{ s}^{-1} \text{ Torr}^{-1}$$

$$= 8.58 \times 10^{-13} \text{ kg s}^{-1}$$

$$b_{\text{square}} = \frac{7 \mu_p^2 A p}{y_0^2} = \frac{7 (3.7 \times 10^{-2}) (2 \times 10^{-6})^2 (7 \times 4 \times 10^{-14}) (0.1)}{(3 \times 10^{-6})^2}$$

$$= 0.322 \times 10^{-12} \text{ kg s}^{-1} \quad (< 50\% \text{ of Comette})$$

$$Q = \frac{M_{\text{eff}} \omega_1}{b_{\text{tot}}} = \frac{(0.07 \times 10^{-12} \text{ kg}) (0.735 \times 10^6 \text{ rad s}^{-1})}{(8.58 + 0.322) \times 10^{-12} \text{ kg s}^{-1}}$$

$$Q = 5.4 \times 10^5 \quad - \text{estimate is high.}$$

c) Find the DC displacement of the tine and the amplitude of its resonance from your answers in (a) and (b).

$$\text{DC displacement: } y_f = F_{\text{ac}}/k = \frac{3.54 \text{ nN}}{0.47 \text{ nN/nm}} = 7.5 \text{ nm}$$

$$\hat{y} = Q \left( \frac{F_{\text{ac}}}{k} \right) = (5.4 \times 10^5) \left( \frac{7.08 \text{ pn}}{0.47 \text{ nN/nm}} \right)$$

$$\hat{y} = 810 \text{ nm} = 0.81 \mu\text{m} \quad 15 \text{ pm}$$

d) Assuming that the lower tine has the same amplitude as the upper tine (but opposite phase), find the current through the comb electrode at resonance.

$$i_s = V_p \frac{dc_s}{dt} = V_p \frac{dc_s}{dy} \frac{dy}{dt} \quad y(t) = \hat{y} \cos \omega t$$

$$\frac{N \epsilon_0 h}{g_0} = 283 \text{ pF/m} \quad \omega = \omega_1$$

$$i_s(t) = \frac{-\omega}{A} 5V \cdot (283 \frac{\text{pF}}{\text{m}}) \cdot (810 \times 10^{-9} \text{ m}) \sin \omega t$$

$$i_s(t) = (0.84 \text{ nA}) \sin \omega t$$