

HW 5 p1

$\rho = 100 \Omega\text{-cm}$ for boron means $N_B = 1.3 \times 10^{14} \frac{\text{At}}{\text{cm}^3}$

(from tables, charts, books, internet, etc.)

$$1.3 \times 10^{14} \frac{\text{At}}{\text{cc}} \left(\frac{1 \text{ cm}}{10^4 \mu\text{m}} \right)^3 = 130 \frac{\text{boron atoms}}{\text{cubic micron}}$$

(compare to ~ 50 billion Si atoms/cubic micron)

HW 5 p2 to get 0.1 mm range: P $\sim 70\text{-}80 \text{ keV}$
B $\sim 30 \text{ keV}$

HW 5 p3 $\frac{(5 \times 10^{15} \frac{\text{atom}}{\text{cm}^2})}{2 \times 10^{-4} \text{ cm}} = 2.5 \times 10^{19} \frac{\text{atom}}{\text{cc}} \Rightarrow \rho = 2.7 \times 10^{-3} \Omega\text{-cm}$

HW 5 p4

weight = $mg = (70 \text{ kg})(9.8 \frac{\text{m}}{\text{s}^2}) \approx 700 \text{ N}$

$$F_{\text{max}} = \sigma_{\text{max}} A = \sigma_{\text{max}} \frac{D^2 \pi}{4}$$

$$D = \sqrt{\frac{4}{\pi} \frac{700 \text{ N}}{\sigma_{\text{max}}}}$$

matl	σ_{max} MPa	D
steel	2000 (best ultimate)	0.6 mm
SS	8000	0.3 mm
Al (5083)	345	1.4 mm

HW 5 p5

In a safety-critical application, I would use at least a factor of 2 margin below the yield strength, (not the ultimate tensile strength) for the metals.

$$\frac{1}{2} \sigma_{\text{yield, Al}} \approx 100 \text{ MPa} \quad D = 2.6 \text{ mm}$$

$$\frac{1}{2} \sigma_{\text{yield, Steel}} \approx 300 \text{ MPa} \quad D = 1.5 \text{ mm}$$

For a brittle material like Silicon, which might have stress concentrations due to surface defects, I'd want at least 10x safety margin, maybe 100x!

$$D = 1 \text{ mm? no way!}$$

$$3 \text{ mm? maybe (100x!)}$$

HW 5 p6 Silicon has a large linear elastic range and no hysteresis, so it will make a reliable resonator. The fact that it's brittle is no big deal unless you drop it. Properly designed stops can prevent fracture even then.

HW5 p7 I gave the properties for spider silk as $E = 60 \text{ GPa}$

Actually $E \approx 15 \text{ GPa}$ though (my mistake)

$$\epsilon_{\max} = 0.3$$

$$F_{\text{spider}} = mg = (10^3 \text{ kg})(9.8 \frac{\text{m}}{\text{s}^2}) \approx 10^4 \text{ N}$$

$$D_{\text{silk}} = \sqrt{\frac{4}{\pi} \frac{F_{\text{spider}}}{\sigma_{\max}}}$$

$$\sigma_{\max} = 18 \text{ GPa (as stated in problem)}$$

$$= 5 \text{ GPa (actually)}$$

$$D_{\text{silk}} = 0.8 \mu\text{m} \quad \text{as stated}$$

$$= 1.6 \mu\text{m} \quad \text{actually}$$

HW5 p8

$$100 \text{ mm}^3 = (10^{-3} \text{ mm})^2 L$$

$$L = \frac{10^2 \text{ mm}^3}{10^{-6} \text{ mm}^2} = 10^8 \text{ mm} = 100 \text{ km}!$$

HW5 p9

Assuming a constant cross section, and ignoring the change in gravitational force w/ altitude, we get the weight at height $h \Rightarrow$ is

$$F(h) = mg = \rho A h g$$

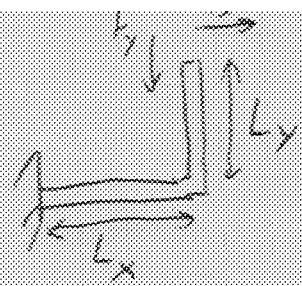
and the stress on the cross-section is:

$$\sigma(h) = \frac{F(h)}{A} = \rho h g$$

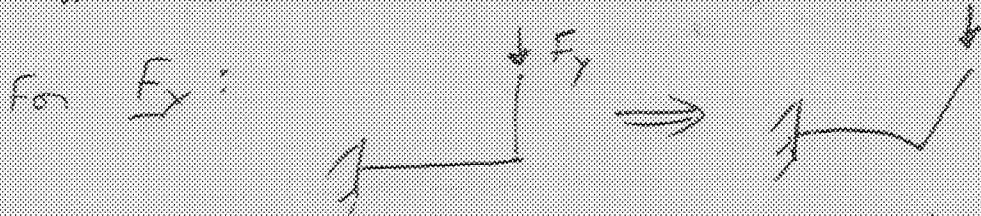
$$h = \frac{\sigma_{\max}}{\rho g}$$

matl)	σ_{\max} [GPa]	ρ [$\frac{\text{g}}{\text{cc}}$]	h [km]
SCS	8 GPa	2.3	350
steel	2	7.9	250
Al	0.345	2.7	128
dragline silk (spider)	5 GPa	~ 1	500
carbon fiber	6 GPa	2	300

HW #5 p10



A force in either x or y direction will cause both x and y deflection.



If we're looking for a spring constant we ~~can't ignore~~ *only want* to think about small deflections. Don't worry about the nonlinear effect that you get when the tip of the beam moves in x.

$$\Delta y = C_{yy} F_y \quad C_{yy} = \frac{1}{K_{yy}} = \frac{L_x^3}{3EI}$$

(recall: $y' = \frac{F(L-x) + M_0}{EI}$)

$$y' = \frac{F(Lx - \frac{x^2}{2}) + M_0 x}{EI} \Rightarrow \Theta(L) = \frac{L^2}{2EI} F + \frac{L}{EI} M_0$$

$$y = \frac{F(L\frac{x^2}{2} - \frac{x^3}{6}) + M_0 \frac{x^2}{2}}{EI} \Rightarrow y(L) = \frac{L^3}{3EI} F + \frac{L^2}{2EI} M_0$$

$$\Delta x = \Theta L_y \quad \Theta = \frac{L_x^2}{2EI} F_y \quad \left(\text{we don't really care about } \Delta x \text{ for } F_y, \text{ but just for completeness} \right)$$

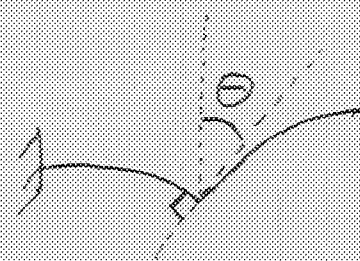
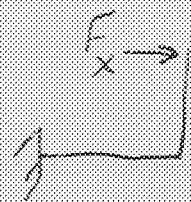
$$\Delta x = \underbrace{\frac{L_y L_x^2}{2EI}}_{C_{xy}} F_y$$

Now we have two coefficients in the compliance matrix:

$$\begin{bmatrix} \Delta x \\ \Delta y \end{bmatrix} = K^{-1} \begin{bmatrix} F_x \\ F_y \end{bmatrix} = \begin{bmatrix} C_{xx} & C_{xy} \\ C_{yx} & C_{yy} \end{bmatrix} \begin{bmatrix} F_x \\ F_y \end{bmatrix}$$

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For F_x



There are 2 parts to the x deflection.

1) simple bending of the vertical beam x_1

2) θ deflection of horizontal beam, ~~goodly~~ x_2

(again, think small deflections and ignore geometric nonlinear)

$$\Delta x = x_1 + x_2$$

$$x_1 = \frac{L_y^3}{3EI} F_x$$

$$x_2 = \theta L_x \quad \theta = \frac{L_x}{EI} M \quad M = L_y F_x$$

$$= \frac{L_x L_y}{EI} F_x$$

$$= \frac{L_x L_y^2}{EI} F_x$$

$$\Delta x = \left(\frac{L_y^3}{3EI} + \frac{L_x L_y^2}{EI} \right) F_x$$

$$\Delta y = \frac{L_x^2}{2EI} M = \frac{L_x^2 L_y}{2EI} F_x \quad (\text{don't need this one})$$

Overall

$$\begin{bmatrix} \Delta x \\ \Delta y \end{bmatrix} = \frac{1}{EI} \begin{bmatrix} L_y^3/3 + L_x L_y^2 & L_y L_x^2/2 \\ L_x L_y^2 & L_x^3/3 \end{bmatrix} \begin{bmatrix} F_x \\ F_y \end{bmatrix}$$

$$\text{Need } C_{xx} = C_{yy} \quad \frac{L_y^3}{3} + L_x L_y^2 = \frac{L_x^3}{3} \quad \text{Let } L_y = \alpha L_x$$

$$\text{then } \alpha^3 + 3\alpha^2 - 1 = 0$$

$$\alpha = 0.5321 \text{ is only positive root}$$