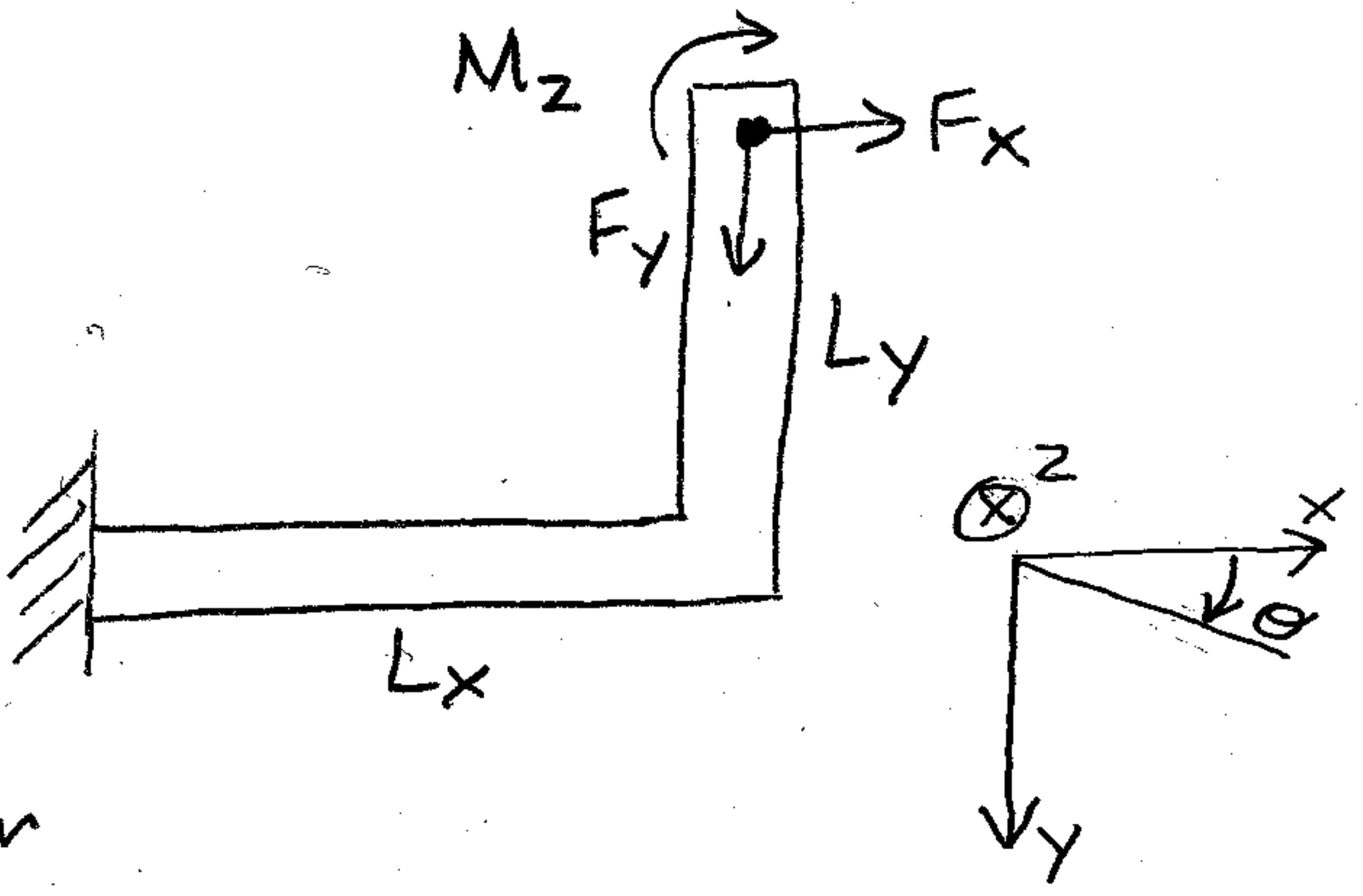
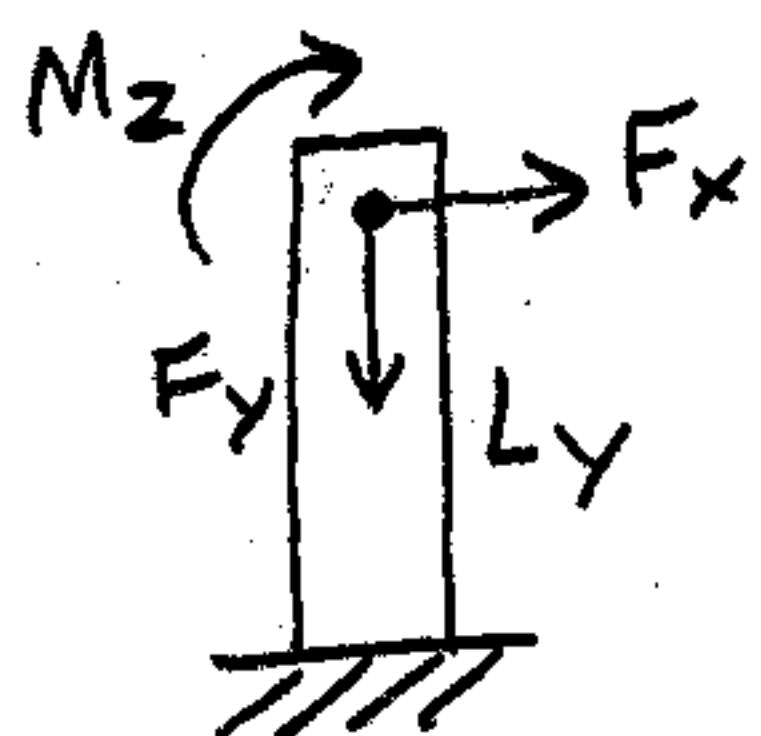


F_x , F_y and M_z result in
displacements v_x , v_y , v_θ

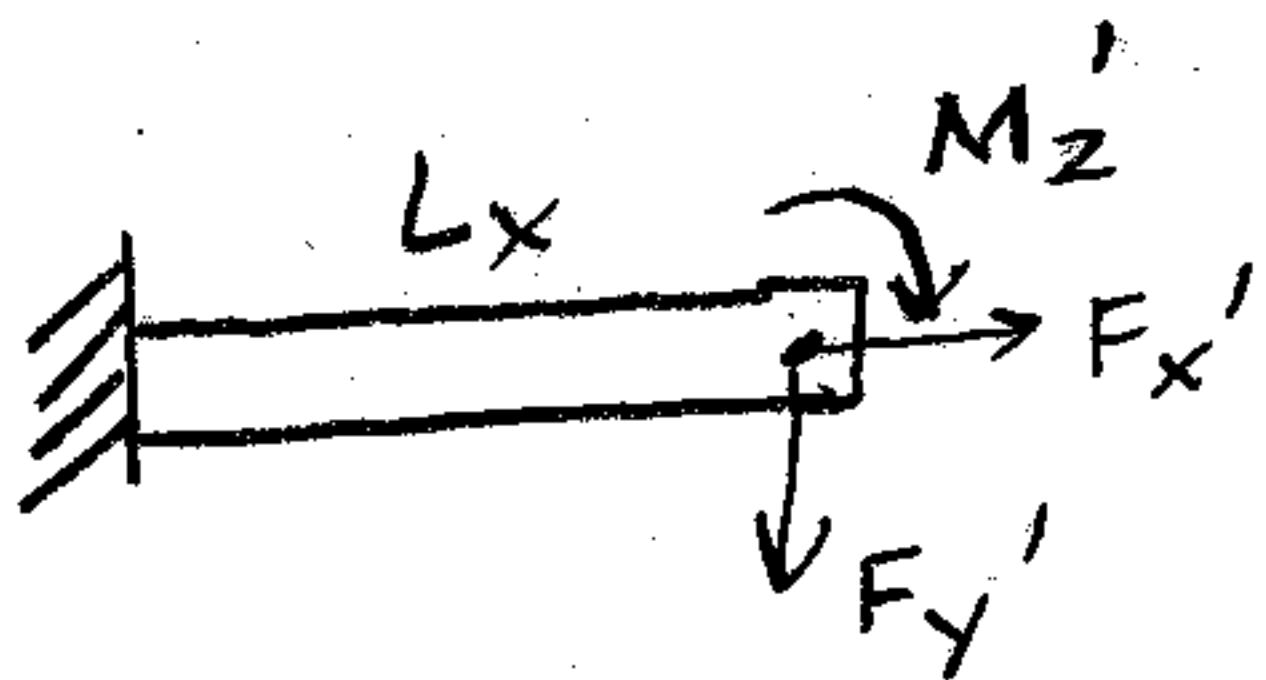


Split problem into two, and take
linear combination for final answer

$$\textcircled{1} \quad v_{x1}, v_{y1}, v_{\theta1}$$



$$\textcircled{2} \quad v_{x2}, v_{y2}, v_{\theta2}$$

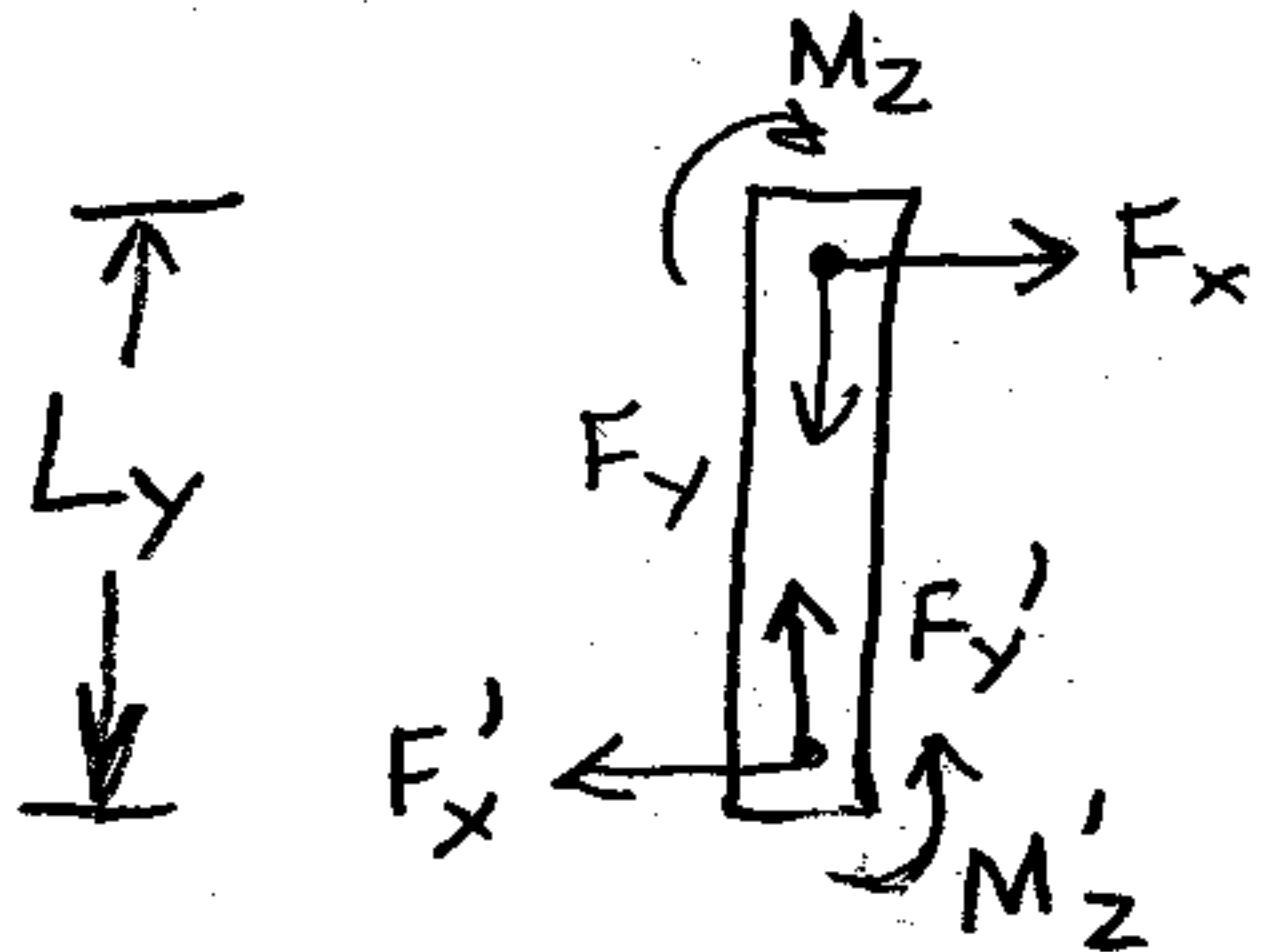


$$\textcircled{1} \quad v_{x1} = \frac{L_y^3}{3EI} F_x + \frac{L_y^2}{2EI} M_z$$

$$v_{y1} = 0 \quad (\text{no axial compliance})$$

$$v_{\theta1} = \frac{L_y^2}{2EI} F_x + \frac{L_y}{EI} M_z$$

\textcircled{2} Find reaction forces - balance forces & moments in free body diagram



$$0 = F_x - F_x' \Rightarrow F_x' = F_x$$

$$0 = F_y - F_y' \Rightarrow F_y' = F_y$$

$$0 = M_z + F_x L_y - M_z'$$

$$\Rightarrow M_z' = M_z + F_x L_y$$

$$\text{check } 0 = M_z + F_x' L_y - M_z'$$

$$\Rightarrow M_z' = M_z + F_x' L_y = M_z + F_x L_y \quad \checkmark$$

$$V_{x2} = 0 \quad (\text{no axial compliance})$$

$$V_{y2} = \frac{L_x^3}{3EI} F_y' + \frac{L_x^2}{2EI} M_z'$$

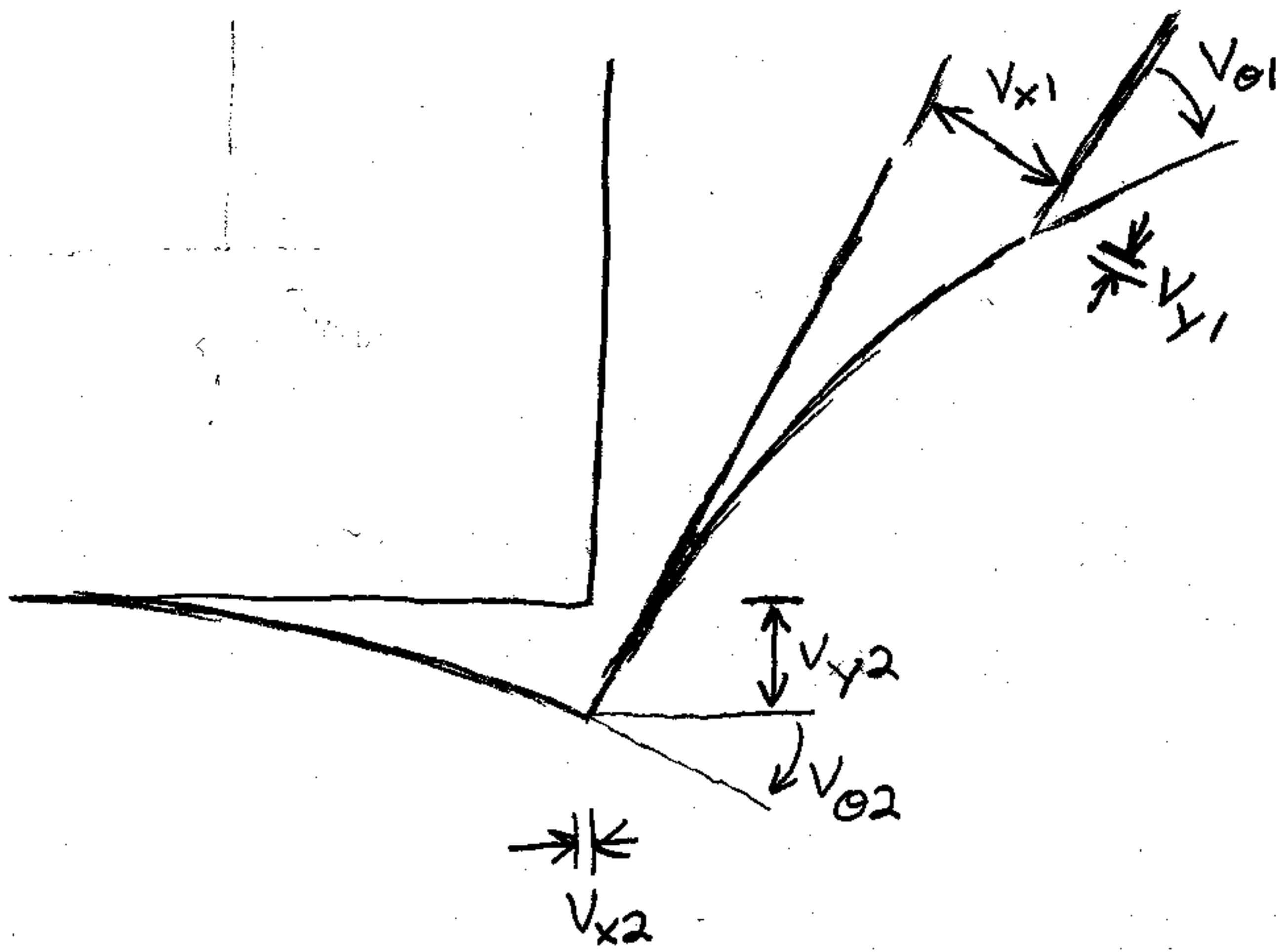
$$= \frac{L_x^3}{3EI} F_y + \frac{L_x^2}{2EI} (M_z + F_x L_y)$$

$$= \frac{L_x^2 L_y}{2EI} F_x + \frac{L_x^3}{3EI} F_y + \frac{L_x^2}{2EI} M_z$$

$$V_{\theta 2} = \frac{L_x^2}{2EI} F_y' + \frac{L_x}{EI} M_z'$$

$$= \frac{L_x^2}{2EI} F_y + \frac{L_x}{EI} (M_z + F_x L_y)$$

$$= \frac{L_x L_y}{EI} F_x + \frac{L_x^2}{2EI} F_y + \frac{L_x}{EI} M_z$$



$$\begin{aligned} V_x &= V_{x2} + L_y \sin V_{\theta 2} + V_{x1} \cos V_{\theta 2} + V_{y1} \sin V_{\theta 2} \\ &= V_{x2} + L_y V_{\theta 2} + V_{x1} + V_{y1} V_{\theta 2} \end{aligned}$$

$$\begin{aligned} V_y &= V_{y2} + L_y (1 - \cos V_{\theta 2}) + V_{y1} \cos V_{\theta 2} + V_{x1} \sin V_{\theta 2} \\ &= V_{y2} + V_{x1} + V_{x1} V_{\theta 2} \end{aligned}$$

$$V_{\theta} = V_{\theta 2} + V_{\theta 1}$$

This is the one non-zero cross term. It's small, so we'll ignore it.

$$V_x = L_y \left(\frac{L_x L_y}{EI} F_x + \frac{L_x^2}{2EI} F_y + \frac{L_x}{EI} M_z \right) + \frac{L_y^3}{3EI} F_x + \frac{L_y^2}{2EI} M_z$$

$$= \left(\frac{L_x L_y^2}{EI} + \frac{L_y^3}{3EI} \right) F_x + \left(\frac{L_x^2 L_y}{2EI} \right) F_y + \left(\frac{L_x L_y}{EI} + \frac{L_y^2}{2EI} \right) M_z$$

$$V_y = \left(\frac{L_x^2 L_y}{2EI} \right) F_x + \left(\frac{L_x^3}{3EI} \right) F_y + \left(\frac{L_x^2}{2EI} \right) M_z$$

$$V_\theta = \left(\frac{L_x L_y}{EI} + \frac{L_y^2}{2EI} \right) F_x + \left(\frac{L_x^2}{2EI} \right) F_y + \left(\frac{L_x}{EI} + \frac{L_y}{EI} \right) M_z$$

$$\begin{bmatrix} V_x \\ V_y \\ V_\theta \end{bmatrix} = \begin{bmatrix} \frac{3 L_x L_y^2 + L_y^3}{3EI} & \frac{L_x^2 L_y}{2EI} & \frac{2 L_x L_y + L_y^2}{2EI} \\ \frac{L_x^2 L_y}{2EI} & \frac{L_x^3}{3EI} & \frac{L_x^2}{2EI} \\ \frac{2 L_x L_y + L_y^2}{2EI} & \frac{L_x^2}{2EI} & \frac{L_x + L_y}{EI} \end{bmatrix} \begin{bmatrix} F_x \\ F_y \\ M_z \end{bmatrix}$$

if $L_x = L_y \equiv L$, then compliance matrix is:

$$\frac{1}{EI} \begin{bmatrix} \frac{4}{3} L^3 & \frac{1}{2} L^3 & \frac{3}{2} L^2 \\ \frac{1}{2} L^3 & \frac{1}{3} L^3 & \frac{1}{2} L^2 \\ \frac{3}{2} L^2 & \frac{1}{2} L^2 & 2L \end{bmatrix}$$