

7.1

$$U = \frac{1}{2} C V^2 = \frac{1}{2} \frac{\epsilon A}{g} V^2 = \frac{1}{2} \epsilon \frac{t x_0}{g_0 - z} V^2$$

$$F_z = - \frac{dU}{dz} = \frac{1}{2} \epsilon \frac{t x_0}{(g_0 - z)^2} V^2 \quad \text{from one side of the comb}$$

$$\text{Total } F_z = \frac{1}{2} \epsilon t x_0 V^2 \left[\frac{1}{(g_0 - z)^2} - \frac{1}{(g_0 + z)^2} \right]$$

7.2

To find spring constant, take coefficient of 1st term in Taylor expansion.
(Find the linear term, that is.)

$$F_z'(z) = \frac{1}{2} \epsilon t x_0 V^2 \left[\frac{-2(-1)}{(g_0 - z)^3} - \frac{-2}{(g_0 + z)^3} \right]$$

$$F_z'(0) = K_e = \frac{1}{2} \epsilon t x_0 V^2 \frac{4}{g_0^3} = \frac{2 \epsilon t x_0 V^2}{g_0^3}$$

• Positive spring constant means it's unstable

Now, we will combine the non-linear electrostatic spring with a linear spring that has twice the stiffness of the electrostatic spring about $z=0$, and a spring that has half the stiffness.

$$\text{Twice } F_z = \frac{1}{2} \epsilon t x_0 V^2 \left[\frac{1}{(g_0 - z)^2} - \frac{1}{(g_0 + z)^2} \right] - 2 \left(\frac{2 \epsilon t x_0 V^2}{g_0^3} \right) z$$

$$\text{Half } F_z = \frac{1}{2} \epsilon t x_0 V^2 \left[\frac{1}{(g_0 - z)^2} - \frac{1}{(g_0 + z)^2} \right] - \frac{1}{2} \left(\frac{2 \epsilon t x_0 V^2}{g_0^3} \right) z$$

In class, we derived that pull-in occurs when $g = \frac{2}{3}g_0$

So, when $V = V_{PI}$, $g = \frac{2}{3}g_0$, displacement of $\frac{1}{3}g_0$

Balance mechanical and electrostatic forces:

$$ky = \frac{1}{2} \epsilon t W V^2 \frac{1}{g^2}$$

$$\frac{E a^3}{L^3} \frac{1}{3}g_0 = \frac{1}{2} \epsilon t W V_{PI}^2 \frac{1}{\left(\frac{2}{3}g_0\right)^2}$$

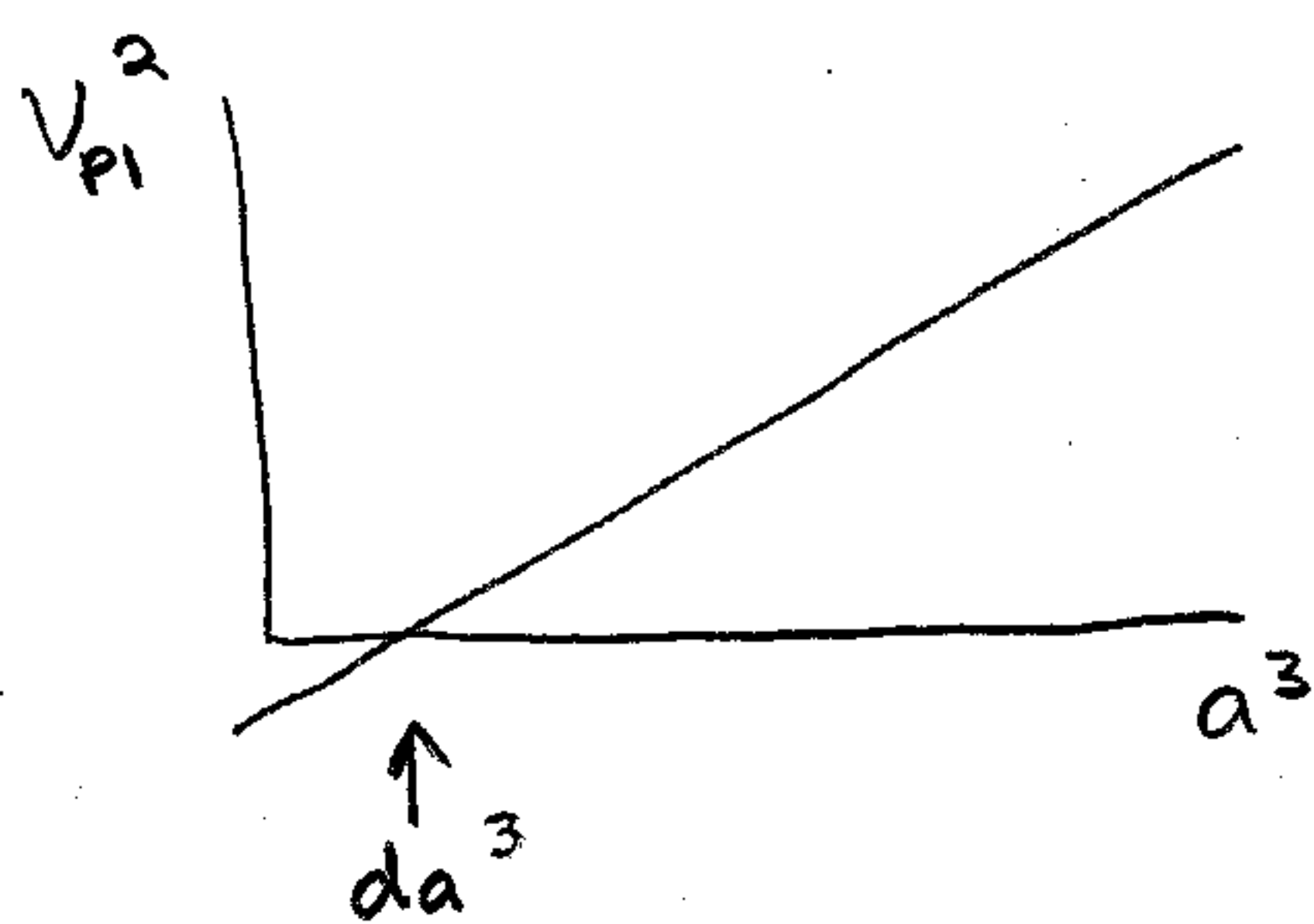
$$V_{PI}^2 = \frac{8 E g_0^3 a^3}{27 W L^3 \epsilon}$$

Pick data points where g_0, L, W are constant, then

$$V_{PI}^2 = \underbrace{\frac{8 E g_0^3}{27 \epsilon W L^3}}_{\text{Constant}} (a + da)^3$$

da or 2 da?
Just depends on
how you define it.

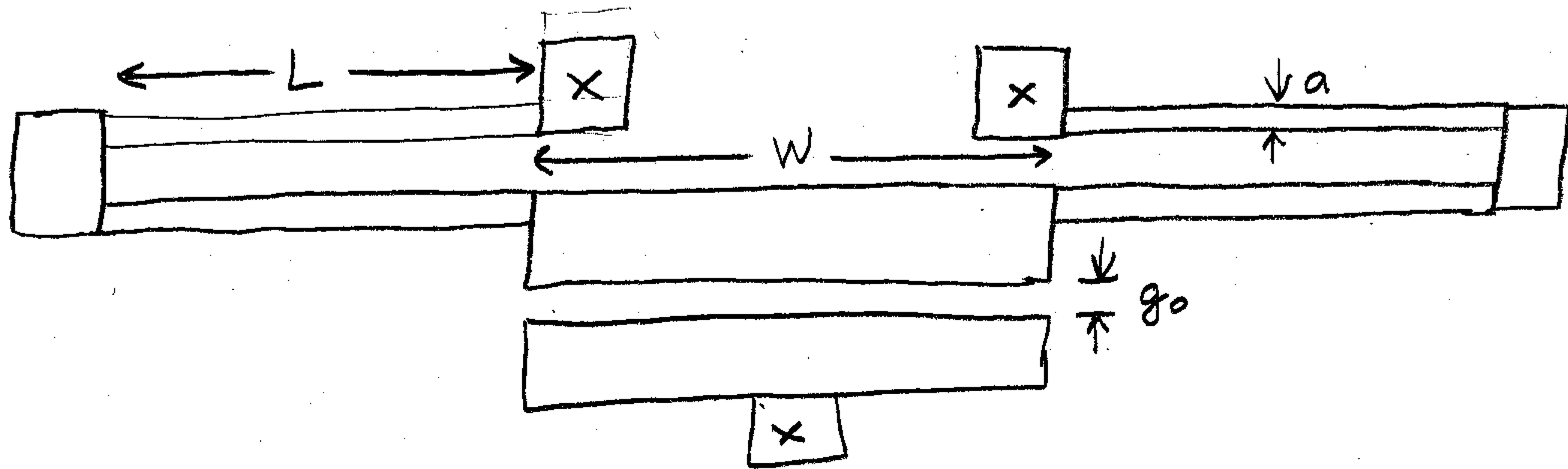
Plot V_{PI}^2 vs. a^3 . Fit points to a linear curve.



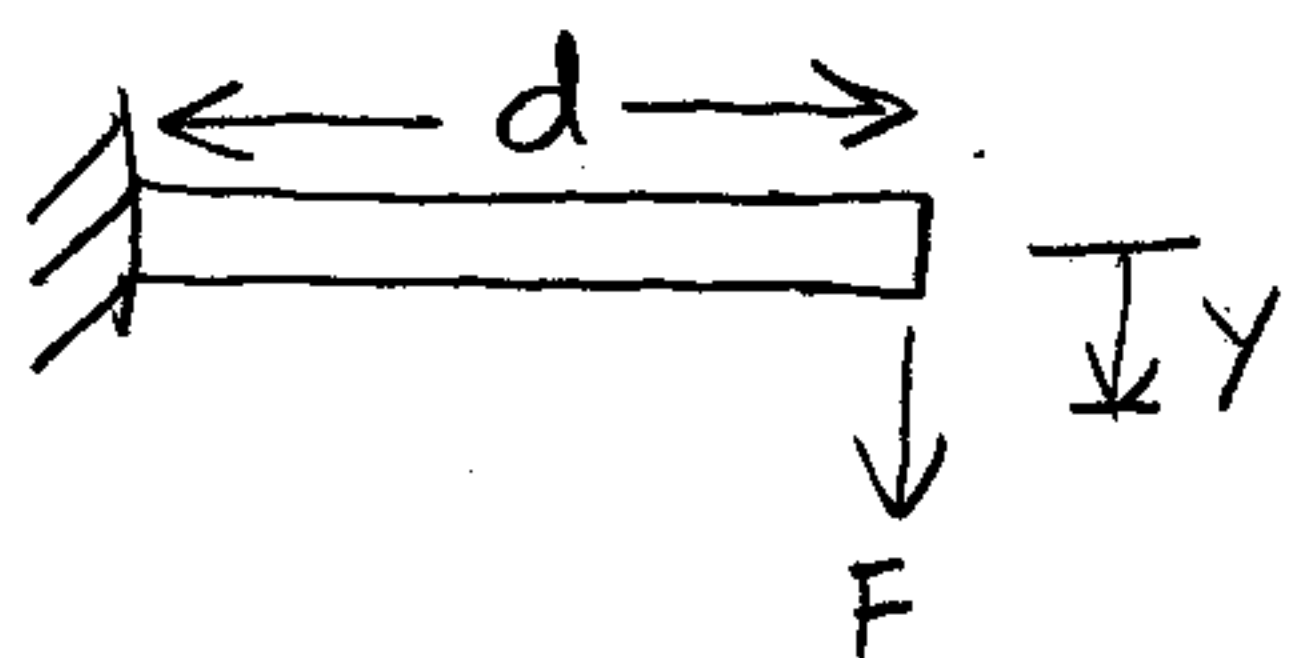
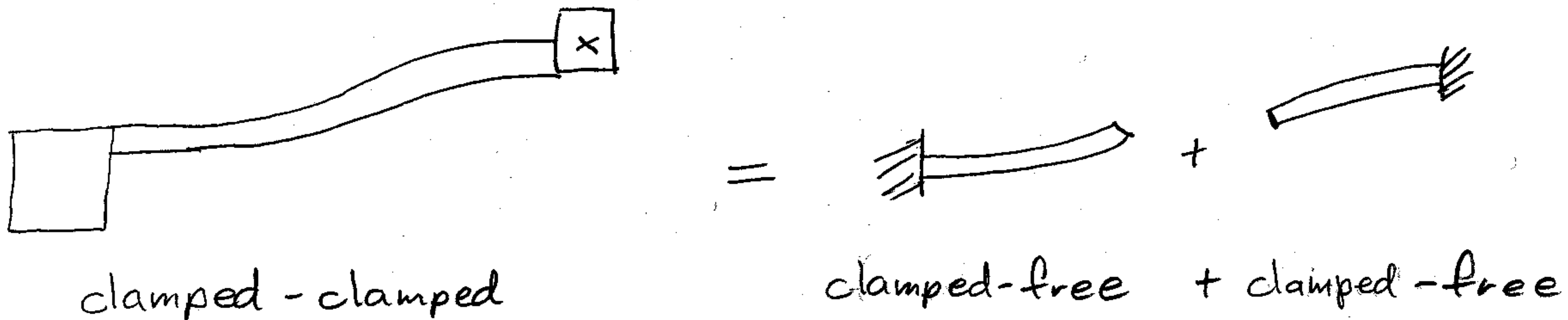
Slope is $\frac{8 E g_0^3}{27 \epsilon W L^3}$, so you
can extract value of E
X-intercept gives da^3

Similarly, find g_0 by holding a, L, W constant

7.3



First find mechanical spring constant



We know for a clamped-free beam,

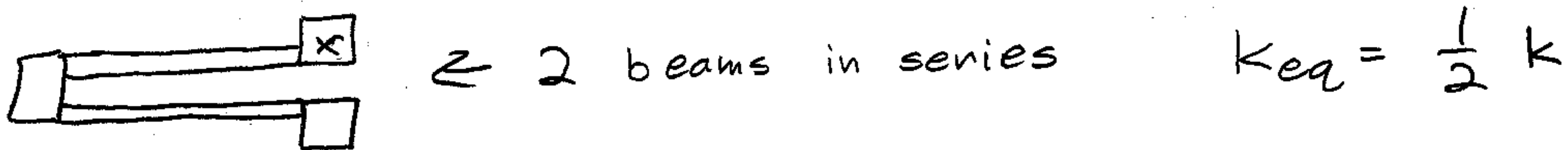
$$y = \frac{d^3}{3EI} F$$

Spring formula $F = -ky \Rightarrow k = \frac{3EI}{d^3}$

* clamped-free beam of length $\frac{L}{2} \Rightarrow k = \frac{3EI}{(\frac{L}{2})^3} = \frac{24EI}{L^3}$

clamped-clamped beam of length L

equivalent to two * beams in series $\Rightarrow k = \frac{12EI}{L^3}$



• Mechanical Spring Constant $k = \frac{12EI}{L^3} = \frac{Ea^3t}{L^3}$

$$I = \frac{3at^3}{12}$$